

# Low Skew TTL PLL Clock Driver With Integrated Loop Filter

QS5931T ADVANCE INFORMATION

#### FEATURES/BENEFITS

- · Six low noise TTL level outputs
- Q outputs, Q/2 output
- <250ps output skew, Q0-Q4</li>
- Outputs 3-state and reset while OE/RST low
- · PLL disable feature for low frequency testing
- · Internal loop filter RC network
- Internal VCO/2 option
- Balanced drive outputs ± 24mA
- 80MHz maximum frequency
- · Industrial temperature range
- Available in space saving QSOP package

#### DESCRIPTION

The QS5931T Clock Driver uses an internal phase locked loop (PLL) to lock low skew outputs to a reference clock input. Six outputs are available: Q0-Q4, Q/2. Careful layout and design ensure <250ps skew between the Q0-Q4, and Q/2 outputs. The QS5931T includes an internal RC filter which provides excellent jitter characteristics and eliminates the need for external components. Various combinations of feedback and a divide-by-2 in the VCO path allow applications to be customized for linear VCO operation over a wide range of input SYNC frequencies. The PLL can also be disabled by the PLL EN signal to allow low frequency or DC testing. The QS5931T is designed for use in cost sensitive highperformance computing systems, workstations, multiboard computers, networking hardware, and mainframe systems. Several can be used in parallel or scattered throughout a system for guaranteed low skew, system-wide clock distribution networks. In the QSOP package, the QS5931T clock driver represents the best value in small form factor, highperformance clock management products.

For more information on PLL clock driver products, see Application Note AN-22A.

Figure 1. Functional Block Diagram

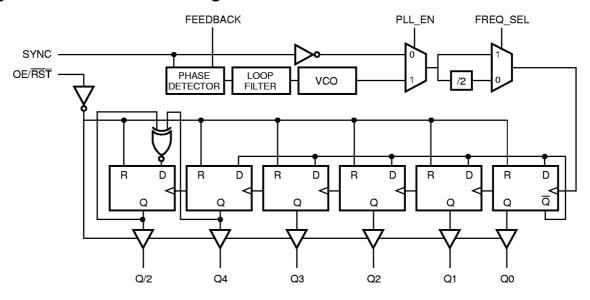
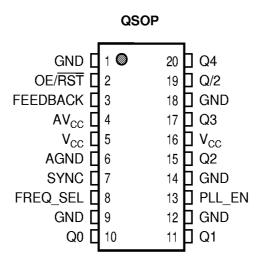


Figure 2. Pin Configuration (All Pins Top View)



**Table 1. Pin Description** 

Pin Name	I/O	Functional Description
SYNC		Reference clock input
FREQ_SEL	_	VCO frequency select. For choosing optimal VCO operating frequency depending on input frequency. HIGH is for higher frequencies, LOW is for lower frequencies.
FEEDBACK	_	PLL feedback input which is connected to either a Q or a Q/2 output. External feedback provides flexibility for different output frequency relationships. See the Frequency Selection Table for more information.
Q0-Q4	0	Clock outputs
Q/2	0	Clock output. Matched in phase, but frequency is half the Q frequency.
OE/RST	_	Output enable/asynchronous reset. Resets all output registers. When 0, all outputs are held in a tri-stated condition. When 1, outputs are enabled.
PLL_EN	I	PLL enable. Enables and disables the PLL. Allows the SYNC input to be single-stepped for system debug.
V <sub>cc</sub>		Power supply for output buffers.
AV <sub>CC</sub>	_	Power supply for phase lock loop and other internal circuitries.
GND	_	Ground supply for output buffers.
AGND		Ground supply for phase lock loop and other internal circuitries.

## **Table 2. Absolute Maximum Ratings**

Supply Voltage to Ground	
DC Input Voltage V <sub>IN</sub>	
Maximum Power Dissipation At T <sub>A</sub> = 85°C	
T <sub>STG</sub> Storage Temperature	–65° to +150°C

**Note:** Stresses greater than those listed under absolute maximum ratings may cause permanent damage to QSI devices that result in functional or reliability type failures.

## **Table 3. Output Frequency Specifications**

Industrial:  $T_A = -40$ °C to +85°C,  $V_{CC} = 5.0V \pm 10\%$ 

Symbol	Description	-50	-66	-80	Units
F <sub>MAX_Q</sub>	Max Frequency, Q0-Q4	50	66	80	MHz
F <sub>MAX_Q/2</sub>	Max Frequency, Q/2	25	33	40	MHz
$F_{MIN_{Q}}$	Min Frequency, Q0-Q4	10	10	10	MHz
F <sub>MIN_Q/2</sub>	Min Frequency, Q/2	5	5	5	MHz

**Table 4. Frequency Selection Table** 

FREQ_SEL	Output Used for Feedback		e SYNC <sup>(1)</sup> (MHz) Max	Output Fr Relatio Q/2	equency onships Q0-Q4
HIGH	Q/2	$F_{MIN_{Q/2}}$	F <sub>MAX_Q/2</sub>	SYNC	SYNC x 2
HIGH	Q0-Q4	F <sub>MIN_Q</sub>	F <sub>MAX_Q</sub>	SYNC/2	SYNC
LOW	Q/2	F <sub>MIN_Q/2</sub> /2	F <sub>MAX_Q/2</sub> /2	SYNC	SYNC x 2
LOW	Q0-Q4	$F_{MIN_Q}/2$	F <sub>MAX_Q</sub> /2	SYNC/2	SYNC

#### Note:

Operation in the specified SYNC frequency range guarantees that the VCO will
operate in its optimal range of 20MHz to F<sub>MAX\_Q</sub> x 2. Operation with Sync inputs
outside specified frequency ranges may result in invalid or out-of-lock outputs.
FREQ\_SEL only affects VCO frequency and does not affect output frequencies.

# Table 5. Capacitance

 $T_A = 25^{\circ}C$ , f = 1MHz,  $V_{IN} = 0V$ 

	QS		
Pins	Тур	Max	Unit
C <sub>IN</sub>	3	4	pF
C <sub>OUT</sub>	4	5	pF

Note: Capacitance is characterized but not tested.

## **Table 6. DC Electrical Characteristics Over Operating Range**

Industrial:  $T_A = -40^{\circ}C$  to +85°C,  $V_{CC} = 5.0V \pm 10\%$ 

Symbol	Parameter	Test Conditions	Min	Тур	Max	Unit
$V_{IH}$	Input HIGH Voltage	Guaranteed Logic HIGH Level	2.0			٧
V <sub>IL</sub>	Input LOW Voltage	Guaranteed Logic LOW Level			8.0	٧
V <sub>OH</sub>	Output HIGH Voltage	V <sub>CC</sub> = Min., I <sub>OH</sub> = -24mA	2.4			٧
		$V_{CC} = Min., I_{OH} = -100 \mu A$	3.0			V
V <sub>OL</sub>	Output LOW Voltage	V <sub>CC</sub> = Min., I <sub>OL</sub> = 24mA			0.45	٧
		$V_{CC} = Min., I_{OL} = 100\mu A$			0.2	V
V <sub>H</sub>	Input Hysteresis			100		mV
I <sub>OZ</sub>	Output Leakage Current	V <sub>OUT</sub> = V <sub>CC</sub> or V <sub>OUT</sub> = GND,			5	μА
		V <sub>CC</sub> = Max., Outputs disabled				
I <sub>IN</sub>	Input Leakage Current	$V_{CC} = Max., V_{IN} = V_{CC} \text{ or } V_{IN} = GND$			5	μА

## **Table 7. Power Supply Characteristics**

Industrial:  $T_A = -40$ °C to +85°C,  $V_{CC} = 5.0V \pm 10$ %

Symbol	Parameter	Test Conditions	Тур	Max	Unit
I <sub>ccq</sub>	Quiescent Power Supply Current	V <sub>CC</sub> = Max., OE/ <del>RST</del> = Low, SYNC = Low, All outputs unloaded		1	mA
Δl <sub>CC</sub>	Power Supply Current per Input HIGH	$V_{CC} = Max., V_{IN} = 3.4V$	0.7	1.5	mA
I <sub>CCD</sub>	Dynamic Power Supply Current <sup>(1)</sup>	$V_{CC} = Max., C_L = 0pF$	_	0.1	mA/ MHz

### Note:

1. Guaranteed by characterization but not tested.

## **Table 8. Switching Characteristics Over Operating Range**

Industrial:  $T_A = -40$ °C to +85°C,  $V_{CC} = 5.0$ V  $\pm 10$ %

Symbol	Description <sup>(1)</sup>	Min	Max	Unit
t <sub>SKR</sub>	Output Skew Between Rising Edges, Q0-Q4 and Q/2(2,3)	_	250	ps
t <sub>SKF</sub>	Output Skew Between Falling Edges, Q0-Q4, and Q/2(2,3)	_	350	ps
t <sub>PW</sub>	Pulse Width, Q0-Q4, Q/2 outputs, 80MHz(2)	T <sub>CY</sub> /2 -0.4	$T_{CY}/2 + 0.4$	ns
t∪	Cycle to Cycle Jitter(2,5)	_	0.25	ns
t <sub>PD</sub>	SYNC Input to Feedback Delay(2,6)	-100	400	ps
t <sub>LOCK</sub>	SYNC to Phase Lock	_	10	ms
t <sub>PZH</sub> t <sub>PZL</sub>	Output Enable Time, OE/RST LOW to HIGH(4)	0	7	ns
t <sub>PHZ</sub>	Output Disable Time, OE/RST HIGH to LOW(2,4)	0	6	ns
$t_R$ , $t_F$	Output Rise/Fall Times, 0.8V-2.0V(2)	0.3	1.5	ns

#### Notes:

- 1. See Figure 3 for test load and termination. Test circuit 1 is used for output enable/disable parameters. Test circuit 2 is used for all other timing parameters.
- 2. This parameter is guaranteed by characterization but not tested.
- 3. Skew specifications apply under identical environments (loading, temperature, V<sub>CC</sub>, device speed grade).
- 4. Measured in open loop mode PLL EN = 0.
- 5. Jitter is characterized using an oscilloscope, Q output at 20MHz. Measurement is taken one cycle after jitter. See FREQUENCY SELECTION TABLE for information on proper FREQ\_SEL level for specified input frequencies.
- 6. t<sub>PD</sub> measured at device inputs at 1.5V, Q output at 80MHz.

## **Table 9. Input Timing Requirements**

Industrial:  $T_A = -40$ °C to +85°C,  $V_{CC} = 5.0$ V  $\pm 10$ %

Symbol	Description	Min	Max	Unit
t <sub>R</sub> , t <sub>F</sub>	Maximum Input Rise and Fall Times, 0.8V to 2.0V	_	3.0	ns
F <sub>I</sub>	Input Clock Frequency, SYNC(1)	2.5	F <sub>MAX_Q</sub>	MHz
t <sub>PWC</sub>	Input Clock Pulse, HIGH or LOW(2)	2	_	ns
D <sub>H</sub>	Duty Cycle, SYNC <sup>(2)</sup>	25	75	%

#### Notes:

- See Table 3 and Table 4 for more detail on allowable SYNC input frequencies for different speed grades with different FEEDBACK and FREQ\_SEL combinations.
- 2. Input timing requirements are guaranteed by design but not tested. Where pulse width implied by D<sub>H</sub> is less than t<sub>PWC</sub> limit, t<sub>PWC</sub> limit applies.

## Figure 3. Test Loads and Waveforms

Test circuit 1 is used for output enable/disable parameters. Test circuit 2 is used for all other timing parameters.

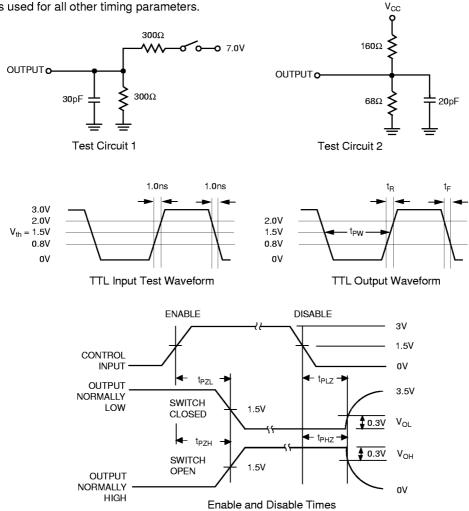
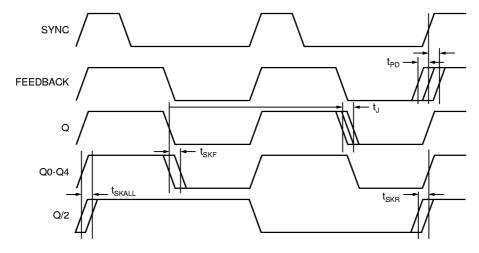


Figure 4. AC Timing Diagram



#### Notes:

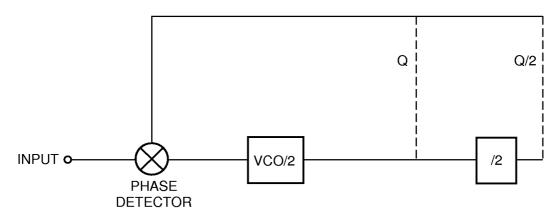
- 1. Figure 4 applies to Q output connected to FEEDBACK.
- 2. All parameters are measured at 1.5V.

#### **PLL OPERATION**

The Phase Locked Loop (PLL) circuit included in the QS5931T provides for replication of incoming SYNC clock signals. Any manipulation of that signal, such as frequency multiplying or inversion is performed by digital logic following the PLL (see the block dia-

gram). The key advantage of the PLL circuit is to provide an effective zero propagation delay between the output and input signals. In fact, adding delay circuits in the feedback path, 'propagation delay' can even be negative! Figure 5 shows a simplified schematic of the QS5931T PLL circuit:

Figure 5. Simplified Diagram of QS5931T Feedback



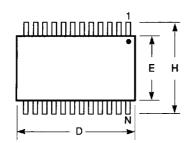
The phase difference between the output and the input frequencies feeds the VCO which drives the outputs. Whichever output is fed back, it will stabilize at the same frequency as the input. Hence, this is a true negative feedback closed loop system. In most applications, the output will optimally have zero phase shift with respect to the input. In fact, the internal loop filter on the QS5931T typically provides within 150ps of phase shift between input and output.

If the user wishes to vary the phase difference (typically to compensate for backplane delays), this is most easily accomplished by adding delay circuits to the feedback path. The respective output used for feedback will be advanced by the amount of delay in the feedback path. All other outputs will retain their proper relationships to that output.



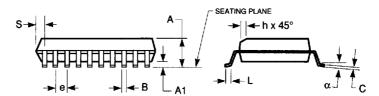
## 150-MIL QSOP - Package Code Q

Quarter-Size Outline Package Plastic Small Outline Gull-Wing



#### Notes:

- 1. Refer to applicable symbol list.
- 2. All dimensions are in inches.
- 3. N is the number of lead positions.
- Dimensions D and E are to be measured at maximum material condition but do not include mold flash. Allowable mold flash is 0.006in. per side.
- Lead coplanarity is 0.004in. maximum.



JEDEC#	MO-137AB			EC# MO-137AB MO-137AD		MO-137AE			MO-137AF			
DWG#	PSS-16A			PSS-20A			PSS-24A			PSS-28A		
Symbol	Min	Nom	Max	Min	Nom	Max	Min	Nom	Max	Min	Nom	Max
Α	0.060	0.064	0.068	0.060	0.064	0.068	0.060	0.064	0.068	0.060	0.064	0.068
A1	0.004	0.006	0.008	0.004	0.006	0.008	0.004	0.006	0.008	0.004	0.006	0.008
В	0.009	0.010	0.012	0.009	0.010	0.012	0.009	0.010	0.012	0.009	0.010	0.012
С	0.007	0.008	0.010	0.007	0.008	0.010	0.007	0.008	0.010	0.007	0.008	0.010
D	0.189	0.193	0.197	0.337	0.341	0.344	0.337	0.341	0.344	0.386	0.390	0.394
E	0.150	0.154	0.157	0.150	0.154	0.157	0.150	0.154	0.157	0.150	0.154	0.157
е	0.	025 BS	С	0.025 BSC		0.025 BSC			0.025 BSC			
н	0.230	0.236	0.244	0.230	0.236	0.244	0.230	0.236	0.244	0.230	0.236	0.244
h	0.010	0.013	0.016	0.010	0.013	0.016	0.010	0.013	0.016	0.010	0.013	0.016
L	0.016	0.025	0.035	0.016	0.025	0.035	0.016	0.025	0.035	0.016	0.025	0.035
N		16		20		24			28			
α	0°	5°	8°	0°	5°	8°	0°	5°	8°	0°	5°	8°
S	0.006	0.009	0.010	0.056	0.058	0.060	0.031	0.033	0.035	0.031	0.033	0.035