

# **FAN5610 LED Driver for White, Blue or any Color LED**

### **Features**

- LED Driver for 4 Parallel-connected LEDs
- Low Voltage Drop (<350mV) to Support Direct Li-ion Applications with Low VF LEDs
- Independent Control Loop for Each LED
- Regulated, Matched Constant Current in LEDs
- No External Components
- No EMI, No Switching Noise
- Built-in DAC for Digital and PWM Brightness Control
- Up to 91% Maximum Efficiency
- Up to 84mA (21mA/LED) Bias Current
- 2.7V to 5.5V Input Voltage Range
- Icc < 1µA in Shutdown Mode
- 3mmX3mm MLP-8 Package

# **Applications**

- Cell Phones
- Handheld Computers
- PDA, DSC, MP3 Players
- LCD Display Modules
- Keyboard Backlight
- LED Displays

# **Typical Application**

### **Description**

The FAN5610 generates matched current source drives for a maximum of four LEDs. Since each LED current source has its own self-regulating loop, precise current matching is maintained even if there is a substantial forward voltage spread among the LEDs. LED pre-selection therefore is not required. In order to minimize voltage drop, and maximize efficiency, the value of the internal current sense resistors connected in series with the LEDs is very low (10Ω). This is an important consideration for direct DC-driven white LEDs in battery-powered systems.

The LEDs current can be set to 0mA (OFF Mode), 7mA, 14mA, 21mA with a built-in two-bit digital-to-analog converter. Customized current settings can also be used. When the control bits are set to zero, the internal circuitry is disabled and the quiescent current drops below 1µA.

Both digital input lines (A, B) can be pulse width modulated. Using PWM, any value of average LED current can be obtained within the 1 to 20 mA range. The FAN5610 is available in an 8-lead 3X3 MLP package.



# **Pin Assignment**

D1		<b>GND</b>
D <sub>2</sub>	<b>FAN5610</b>	D4
INB		D3
IN A		

3x3mm 8-LEAD MLP PACKAGE

# **Pin Descriptions**



### **Absolute Maximum Ratings**



### **Recommended Operating Conditions**



### **DC Electrical Characteristics**

(VIN =3.3V to 5.5V, TA = 25 °C, unless otherwise noted. **Boldface** values indicate specifications over the ambient operating temperature range.)



#### **Notes:**

1. Using Mil Std. 883E, method 3015.7(Human Body Model) and EIA/JESD22C101-A (Charge Device Model).

2. The minimum operating voltage depends on the LED's operating voltage, as shown in the "Application Information" section.

# **Block Diagram**



Unless otherwise specified,  $T_A = 25 °C$ , using Fairchild QTLP670IW Super Bright LED.



LED Current vs. Temperature **LED Current vs. Temperature Line Transient Response** 





**LED Current vs. Cathode Voltage**





# **Digital LED Brightness Control**

### **1. Digital Control**

A digital to analog converter selects the following modes of operation: OFF, 7mA, 14mA, 21mA per diode. In addition, by turning the "IN B" pin ON and OFF , the current can be modulated between 8 to 20mA to achieve any Iaverage value.



### **2. Digital Control with PWM**

Any pin can be modulated by a variable duty cycle  $(\delta)$  pulse train. Care should be taken not to use too low frequency, otherwise a flickering effect can be seen.The minimum range is between 100Hz to 5KHz. For a maximum range of LED current, both A&B can be modulated at the same time.

### **Digital Control with PWM**



**A is PWM and B is Low.**  $I_{LED}$  (Average) =  $\delta$  x 7mA where  $\delta$  is Duty Cycle. (Note 3)

**A is High and B is PWM.**  $I_{LED}$  (Average) = 7mA +  $\delta$  x 14mA where  $\delta$  is Duty Cycle. (Note 4, 5)



#### **Notes:**

- 3. Proportionally select the duty cycle to achieve a typical LED current between 1mA to 6mA.
- 4. If any one of inputs A or B is high continuously, the other input can be modulated at a maximum rate of 30kHz. If this is not the case, the maximum rate of modulation should be limited to 1kHz.
- 5. Proportionally select the duty cycle to achieve a typical LED current between 8mA to 20mA.

#### **Digital Control with PWM** (Continued)

#### **A and B are PWM.** ILED (Average) =  $\delta$  x 21mA where  $\delta$  is Duty Cycle. (Note 6)



**Note:**

6. Proportionally select the duty cycle to achieve the desired value of typical LED current between 1mA to 20mA.

### **Application Information**

As seen in the block diagram, the FAN5610 includes four independent current regulators able to maintain a programmable constant current through LEDs, regardless of their forward voltage. This is true over a wide range of input voltage starting from  $V_{F_{max}}$  + 0.35V, where  $V_{F_{max}}$  is the highest forward voltage among the LEDs driven by FAN5610. The independence of current (LED current changes less than  $1\%$ ) with change in  $V_{IN}$  and  $V_F$  for  $V_{IN}$  >  $V_{F (MAX)}$  + 0.35V, is shown in graph below.



**Current Regulation Performance**

Program the LED's brightness by applying continuous voltage level or a PWM signal at the inputs of the built-in digital to analog converter (DAC). When a PWM signal is utilized to drive the DAC inputs, the current through LEDs is switched between two levels with the PWM signal frequency. Consequently, the average current changes with the duty cycle. The LED current waveform tracks the PWM signal, so the LED brightness depends upon the duty cycle.

Four white LEDs the spectral composition is optimal at a current level specified by the manufacturer. The DAC inputs should be programmed to set the current required to achieve white LED spectrum and PWM used for dimming. To maintain the "purest" white, the current through LEDs should be switched between zero and specified current level (usually around 20mA) corresponding to the white light chromaticity coordinate.

Conversion errors are minimized and the best LED to LED matching is achieved over the entire range of average current settings, when PWM brightness control is used to modulate the LED current between zero and the maximum value  $(A=1, B=1)$ .

### **Application Examples:**

#### Example 1: Drive low V<sub>F</sub> white or blue LEDs directly **from single cell Li-ion**

When using white or blue low  $V_F$  LEDs, and utilizing the drivers low voltage drop, only 3.45V in V<sub>IN</sub> is needed for the full 20mA LED current. Usually at 3.1V, there is still 5mA current available for the LEDs. The single cell Li-ion is utilized in most applications like cell phones or digital still cameras. In most cases, the Li-ion battery voltage level only goes down to 3.0V voltage level, and not down to the full discharge level (2.7V) before requesting the charger.



 $-$  V<sub>DROP</sub>  $\sim 0.35V$ 

- $V_F$  (at 20mA) < 3.1V (Low  $V_F$ )
- $-V$ IN (at 20mA) =VDROP + VF = 3.45V
- $-$  V<sub>IN</sub> (at 5mA Typical)  $\sim$  3.1V

Where  $V_{IN}$  = Single cell Li-ion Voltage

### **Key advantages:**

- No boost circuit needed for the LCD or keyboard backlight
- Drivers directly connected to a Li-ion battery
- No EMI, no switching noise, no boost efficiency lost, no capacitor, and no inductor.

#### **Example 2: Drive high V<sub>F</sub> white or blue LEDs from existing bus from 4.0V to 5.5V**

High V<sub>F</sub> white or blue LEDs have forward-voltage drop in the range of 3.3V to 4.0V. To drive these LEDs with the maximum current of 20mA for maximum brightness, usually requires a boost circuit for a single cell Li-ion voltage range. In some cases, there is already a voltage bus in the system, which can be utilized. Due to the low voltage drop of the FAN5610, V<sub>IN</sub> needs to be only 350mV higher than the voltage VF of LEDs connected to FAN5610.

- $-$  V<sub>DROP</sub>  $\sim 0.35V$
- $V_F$  (at 20mA) = 3.3V to 4.0V (High  $V_F$ )
- $-V_{IN(at 20mA)} \ge V_{DROP} + V_F = 4.35V(max)$

Where  $V_{IN}$  = Existing bus = 5V



#### **Key advantages:**

- No boost circuit needed for LCD or keyboard backlight
- Driver utilizes the existing bus
- Low voltage drop provides the full 20mA LED current at the lowest possible voltage level.

3.30

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### **Mechanical Dimensions**

### **3mmX3mm 8-Lead MLP Package**



BOTTOM VIEW

#### NOTES:

- A. CONFORMS TO JEDEC REGISTRATION MO-229, VARIATION VEEC, DATED 11/2001
- B. DIMENSIONS ARE IN MILLIMETERS.
- C. DIMENSIONS AND TOLERANCES PER ASME Y14.5M, 1994

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