

## FEATURES/BENEFITS

- Pin and function compatible with T.I. Widebus™ and IDT Double-Density™ families
- CMOS power levels: <math><1\mu\text{W}</math> typical standby
- SSOP (PV) and TSSOP (PA) packages
- Low output skew: 0.5ns  $t_{SK(O)}$
- Flow-through pinout for easy layout
- Power off disable allows hot plugging
- Industrial temperature:  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$
- Input hysteresis for noise immunity
- Multiple power and ground pins for low noise

### FCT16646T

- High drive standard FCT-T outputs:  
 $I_{OL} = 64\text{mA}$ ,  $I_{OH} = -32\text{mA}$
- Incident switching for driving buses and large loads

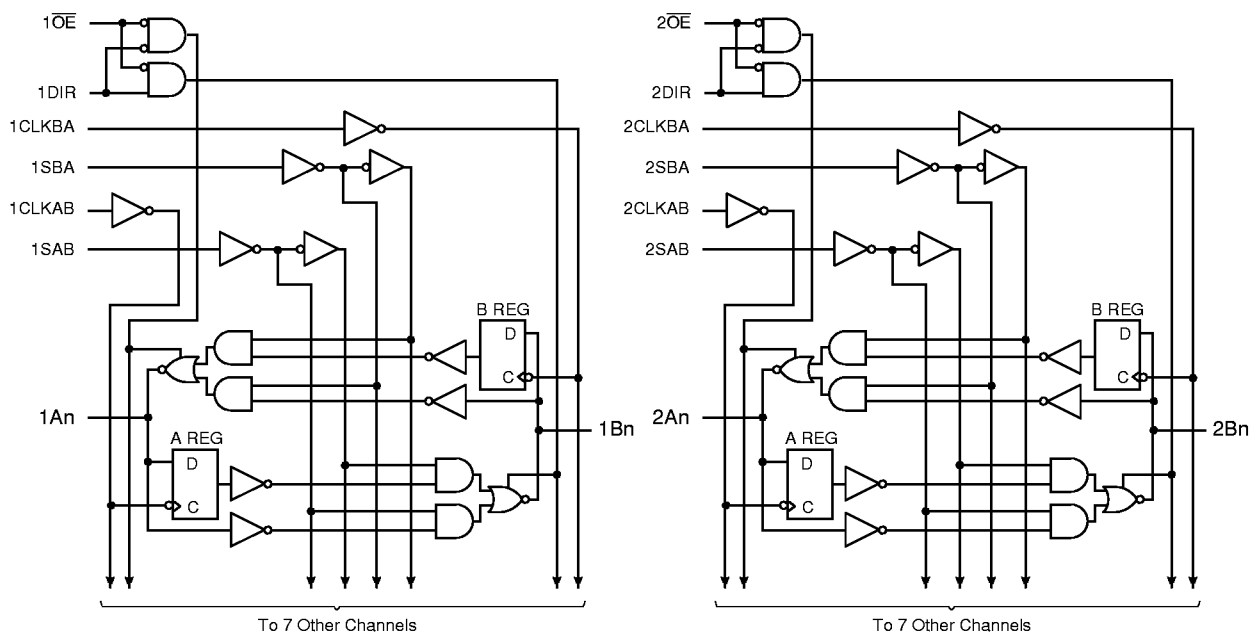
### FCT162646T

- Balanced output drivers:  $\pm 24\text{mA}$
- Reduced switching noise for point to point signals

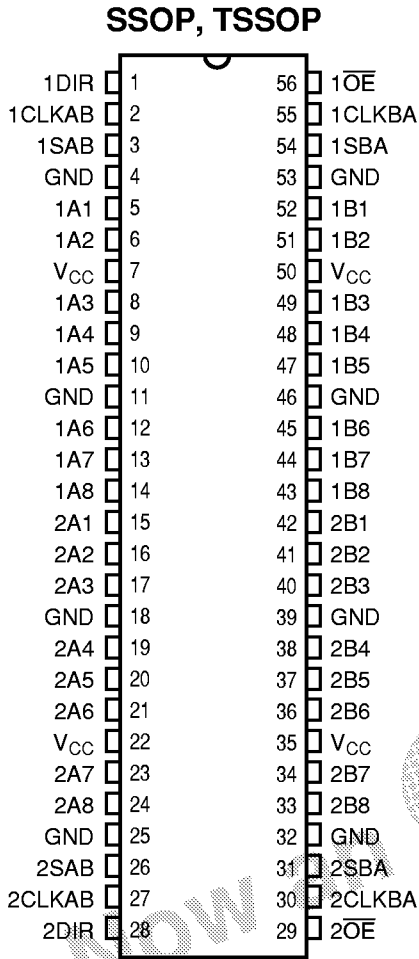
## DESCRIPTION

The FCT16646 family of products are 16-bit bus register transceivers with three-state outputs that are ideal for driving address and data buses. The FCT16646 and FCT162646 are organized for transmission of data between A bus and B bus either directly or from the internal storage registers. Easy board layout is facilitated by the use of flow-through pinouts and byte enable controls provide architectural flexibility for systems designers. All outputs have ground bounce suppression circuitry (see QSI Application Note AN-01) and many power and ground pins provide low ground bounce. To accommodate hot-plug or live insertion applications, both versions of this product were designed not to load an active bus when  $V_{CC}$  is removed. In applications where bus signals are point-to-point or driving light capacitance loads, the balanced drive FCT162646 is recommended.

Figure 1. Functional Block Diagram



**Figure 2. Pin Configuration**  
(All Pins Top View)



**Table 1. Pin Description**

Name	Description
xAx	Data Register A Inputs Data Register B Outputs
xBx	Data Register B Inputs Data Register A Outputs
xCLKAB, xCLKBA	Clock Inputs
xSAB, xSBA	Output Source Select Inputs
xDIR, xOE	Output Enable Inputs

**Table 2. Function Table**

Inputs						Data I/O <sup>(1)</sup>		Operation or Function
xOE	xDIR	xCLKAB	xCLKBA	xSAB	xSBA	xAx	xBx	
H	X	H or L	H or L	x	x	Input	Input	Isolation
H	X	↑	↑	X	X			Store A and B Data
L	L	X	X	X	L	Output	Input	Real Time B Data to A Bus
L	L	X	H or L	X	H			Stored B Data to A Bus
L	H	X	X	L	X	Input	Output	Real Time A Data to B Bus
L	H	H or L	X	H	X			Stored A Data to B Bus

**Notes:**

- The data output functions may be enabled or disabled by various signals at the xOE or xDIR inputs. Data input functions are always enabled; i.e., data at the bus pins will be stored on every LOW-to-HIGH transition on the clock inputs.
- H = HIGH Voltage Level  
L = LOW Voltage Level  
X = Don't Care  
↑ = LOW-to-HIGH Transition

**Table 3. Absolute Maximum Ratings**

Supply Voltage to Ground .....	-0.5V to 7.0V
DC Output Voltage $V_{OUT}$ .....	-0.5V to 7.0V
DC Input Voltage $V_{IN}$ .....	-0.5V to 7.0V
AC Input Voltage (for a pulse width $\leq 20$ ns) .....	-3.0V
DC Input Diode Current with $V_{IN} < 0$ V .....	-20mA
DC Output Diode Current with $V_{OUT} < 0$ V .....	-50mA
DC Output Current Max. Sink Current/Pin .....	120mA
Maximum Power Dissipation .....	1.0 watts
$T_{STG}$ Storage Temperature .....	-65° to 150°C

**Note:** Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to this device resulting in functional or reliability type failures.

**Table 4. DC Electrical Characteristics Over Operating Range**

Recommended Operating Ranges apply unless otherwise noted.

Symbol	Parameter	Test Conditions <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Unit
$V_{IH}$	Input HIGH Voltage	Logic HIGH for All Inputs	2.0	—	—	V
$V_{IL}$	Input LOW Voltage	Logic LOW for All Inputs	—	—	0.8	V
$\Delta V_T$	Input Hysteresis	$V_{TLH} - V_{THL}$ for All Inputs <sup>(4)</sup>	—	100	—	mV
$ I_{IH} $ $ I_{IL} $	Input Current Input HIGH or LOW	$V_{CC} = \text{Max.}, 0 \leq V_{IN} < V_{CC}$	—	—	1	$\mu\text{A}$
$ I_{OZ} $	Off-State Output Current (Hi-Z)	$V_{CC} = \text{Max.}, 0 \leq V_{OUT} \leq V_{CC}$	—	—	1	$\mu\text{A}$
$ I_{OFF} $	Power off leakage	$V_{CC} = 0\text{V}, V_{IN}/V_{OUT} \leq 4.5\text{V}^{(5)}$	—	—	1	$\mu\text{A}$
$I_{OS}$	Short Circuit Current	$V_{CC} = \text{Max.}, V_{OUT} = \text{GND}^{(3,4)}$	-80	-140	-225	mA
$V_{IK}$	Input Clamp Voltage	$V_{CC} = \text{Min.}, I_{IN} = -18\text{mA}$	-	-0.7	-1.2	V

**Notes:**

1. For conditions shown as Min. or Max. use appropriate value specified under Recommended Operating Conditions for the applicable device type.
2. Typical values indicate  $V_{CC} = 5.0\text{V}$  and  $T_A = 25^\circ\text{C}$ .
3. Not more than one output should be tested at one time. Duration of test should not exceed one second.
4. These parameters are guaranteed by design but not tested.
5. The test limit for this parameter is  $\pm 5\mu\text{A}$  at  $T_A = -55^\circ\text{C}$

**Table 5. Capacitance**

$T_A = 25^\circ\text{C}, f = 1\text{MHz}, V_{IN} = 0\text{V}, V_{OUT} = 0\text{V}$

Pins	Typ	Max	Unit
All	6.0	9.0	pF

**Table 6. Recommended Operating Conditions**

Symbol	Parameter	Min	Max	Unit
$V_{CC}$	Supply Voltage	4.5	5.5	V
$V_{IN}$	Input Voltage	0	$V_{CC}$	V
$V_{OUT}$	Voltage Applied to Output or I/O	0	$V_{CC}$	V
$\Delta t/\Delta v$	Input Transition Slew Rate	—	10	ns/V
$T_A$	Operating Free Air Temperature	-40	85	°C

**Table 7. Output Drive Characteristics for FCT16646T**

Symbol	Parameter	Test Conditions <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Unit	
$V_{OH}$	Output HIGH Voltage	$V_{CC} = \text{Min.}$ $V_{IN} = V_{IH} \text{ or } V_{IL}$	$I_{OH} = -3\text{mA}$	2.5	3.4	—	V
			$I_{OH} = -15\text{mA}$	2.4	3.2	—	V
			$I_{OH} = -32\text{mA}^{(4)}$	2.0	3.0	—	V
$V_{OL}$	Output LOW Voltage	$V_{CC} = \text{Min.}$ $V_{IN} = V_{IH} \text{ or } V_{IL}$	$I_{OL} = 64\text{mA}$	—	0.3	0.55	V

**Table 8. Output Drive Characteristics for FCT162646T**

Symbol	Parameter	Test Conditions <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Unit	
$I_{ODL}$	Output LOW Current	$V_{CC} = 5\text{V}$ , $V_{IN} = V_{IH} \text{ or } V_{IL}$ $V_{OUT} = 1.5\text{V}^{(3)}$	60	115	200	mA	
$I_{ODH}$	Output HIGH Current	$V_{CC} = 5\text{V}$ , $V_{IN} = V_{IH} \text{ or } V_{IL}$ $V_{OUT} = 1.5\text{V}^{(3)}$	-60	-115	-200	mA	
$V_{OH}$	Output HIGH Voltage	$V_{CC} = \text{Min.}$ $V_{IN} = V_{IH} \text{ or } V_{IL}$	$I_{OH} = -24\text{mA}$	2.4	3.1	—	V
$V_{OL}$	Output LOW Voltage	$V_{CC} = \text{Min.}$ $V_{IN} = V_{IH} \text{ or } V_{IL}$	$I_{OL} = 24\text{mA}$	—	0.3	0.55	V

**Notes:**

1. For conditions shown as Min. or Max. use appropriate value specified under Electrical Characteristics for the applicable device type.
2. Typical values indicate  $V_{CC} = 5.0\text{V}$  and  $T_A = 25^\circ\text{C}$ .
3. Not more than one output should be shorted and the duration is  $\leq 1$  second.
4. Duration of the condition should not exceed one second.

**Table 9. Power Supply Characteristics**

Symbol	Parameter	Test Conditions <sup>(1)</sup>	Typ <sup>(2)</sup>	Max	Unit	
$I_{CCL}$ $I_{CCH}$ $I_{CCZ}$	Quiescent Power Supply Current	$V_{CC} = \text{Max.}, V_{IN} = \text{GND or } V_{CC}$	5	500	$\mu\text{A}$	
$\Delta I_{CC}$	Supply Current per Input @ TTL HIGH	$V_{CC} = \text{Max.}, V_{IN} = 3.4\text{V}^{(3)}$	0.5	1.5	mA	
$Q_{CCD}$	Supply Current per Input per MHz <sup>(4)</sup>	$V_{CC} = \text{Max.}, \text{Outputs Open One Bit Toggling @ 50\% Duty Cycle } x\text{DIR} = x\overline{\text{OE}} = \text{GND}$	$V_{IN} = V_{CC}$ $V_{IN} = \text{GND}$	75	120	$\mu\text{A}/\text{MHz}$
$I_C$	Total Power Supply Current <sup>(6)</sup>	$V_{CC} = \text{Max.}, \text{Outputs Open One Bit Toggling @ 50\% Duty Cycle } f_I = 5\text{MHz}, f_{CP} = 10\text{MHz (xCLKBA)} x\text{DIR} = x\overline{\text{OE}} = \text{GND}$	$V_{IN} = V_{CC}$ $V_{IN} = \text{GND}$	0.8	1.7 <sup>(5)</sup>	mA
			$V_{IN} = 3.4\text{ V}$ $V_{IN} = \text{GND}$	1.3	3.2 <sup>(5)</sup>	mA
		$V_{CC} = \text{Max.}, \text{Outputs Open Sixteen Bits Toggling @ 50\% Duty Cycle } f_I = 2.5\text{MHz}, f_{CP} = 10\text{MHz (xCLKBA)} x\text{DIR} = x\overline{\text{OE}} = \text{GND}$	$V_{IN} = V_{CC}$ $V_{IN} = \text{GND}$	3.8	6.5 <sup>(5)</sup>	mA
			$V_{IN} = 3.4\text{ V}$ $V_{IN} = \text{GND}$	8.3	20 <sup>(5)</sup>	mA

**Notes:**

- For conditions shown as Min. or Max., use the appropriate values specified under Recommended Operating Conditions for applicable device type.
- Typical values are at  $V_{CC} = 5.0\text{V}$ ,  $+25^\circ\text{C}$  ambient.
- Per TTL driven input ( $V_{IN} = 3.4\text{V}$ ). All Other Inputs at  $V_{CC}$  or GND.
- This parameter is not directly testable, but is derived for use in Total Power Supply Calculations.
- Values for these conditions are examples of the  $I_{CC}$  formula. These limits are guaranteed by design but not tested.
- $I_C = I_{\text{QUIESCENT}} + I_{\text{INPUTS}} = I_{\text{DYNAMIC}}$   
 $I_C = I_{CCQ} + \Delta I_{CC} D_H N_T + I_{CCD} (f_{CP} N_{CP} / 2 + f_I N_I)$   
 $I_{CCQ}$  = Quiescent Current ( $I_{CCL}$ ,  $I_{CCH}$ , and  $I_{CCZ}$ ).  
 $\Delta I_{CC}$  = Power Supply Current for a TTL-High Input ( $V_{IN} = 3.4\text{V}$ ).  
 $D_H$  = Duty Cycle for TTL High Inputs.  
 $N_T$  = Number of TTL High Inputs.  
 $I_{CCD}$  = Dynamic Current Caused by an Input Transition Pair (HLH or LHL).  
 $f_{CP}$  = Clock Frequency for Register devices (Zero for Non-Register Devices).  
 $N_{CP}$  = Number of Clock Inputs at  $f_{CP}$ .  
 $f_I$  = Input Frequency.  
 $N_I$  = Number of Inputs at  $f_I$ .

**Table 10. Switching Characteristics Over Operating Range**

Recommended Operating Ranges apply unless otherwise specified.

$C_{LOAD} = 50\text{pF}$ ,  $R_{LOAD} = 500\Omega$  unless otherwise noted.

Symbol	Description <sup>(1)</sup>	FCT16646T FCT162646T		FCT16646AT FCT162646AT		FCT16646CT FCT162646CT		Unit
		Min	Max	Min	Max	Min	Max	
$t_{PHL}$ $t_{PLH}$	Propagation Delay Bus to Bus	2.0	9.0	2.0	6.3	1.5	5.4	ns
$t_{PZH}$ $t_{PZL}$	Output Enable Time xDIR or x $\overline{OE}$ to Bus	2.0	14.0	2.0	9.8	1.5	7.8	ns
$t_{PHZ}$ $t_{PLZ}$	Output Disable Time <sup>(3)</sup> xDIR or x $\overline{OE}$ to Bus	2.0	9.0	2.0	6.3	1.5	6.3	ns
$t_{PHL}$ $t_{PLH}$	Propagation Delay Clock to Bus	2.0	9.0	2.0	6.3	1.5	5.7	ns
$t_{PHL}$ $t_{PLH}$	Propagation Delay xSAB or xSBA to Bus	2.0	11.0	2.0	7.7	1.5	6.2	ns
$t_{SU}$	Setup Time HIGH or LOW Bus to Clock	4.0	—	2.0	—	2.0	—	ns
$t_H$	Hold Time HIGH or LOW Bus to Clock	2.0	—	1.5	—	1.5	—	ns
$t_W$	Clock Pulse Width <sup>(3)</sup> LOW or HIGH	6.0	—	5.0	—	5.0	—	ns
$t_{SK(O)}$	Output Skew <sup>(2)</sup>	—	0.5	—	0.5	—	0.5	ns

**Notes:**

1. Minimums guaranteed but not tested. See Test Circuit and Waveforms.
2. Skew between any two outputs of the same package switching in the same direction. This parameter is guaranteed by design but not tested.
3. This condition is guaranteed by characterization, but not production tested.