

# **Off-Line Primary Side Sensing Controller with PFC**

### **General Description**

The TPS92314/14A is an off-line controller specifically designed to drive high power LEDs for lighting applications. Features include adaptive constant on-time control and quasiresonant switching. Resonant switching allows for a reduced EMI signature and increased system efficiency. Thus, the device introduces a low external parts count and high level of integration. The control algorithm of TPS92314/14A adjusts the on time with reference to the primary side inductor peak current and secondary side inductor discharge time dynamically, the response time of which is set by an external capacitor.

The over current protection is implemented by a cycle by cycle current limit of the primary inductor current. TPS92314A has a higher OCP threshold which is more suitable for universal line application and TPS92314 can optimize the system cost. Other supervisory features of the TPS92314/14A include VCC over voltage protection and under-voltage lockout, output LEDs over-voltage protection and controller thermal shutdown. The TPS92314/14A is available in 8 pin SOIC package.

#### **Features**

- Regulates LED current without secondary side sensing
- Adaptive ON-time control with inherent PFC
- Critical-Conduction-Mode (CRM) with Zero-Current Detection (ZCD) for valley switching
- Programmable switch turn ON delay
- Programmable Constant ON-Time (COT)
- Over Current Limit Options: TPS92314: 1.15V TPS92314A: 2.0V
- Advanced Over Current and Over Voltage Protection
- Internal Over-temperature Protection
- 8-Pin SOIC Package

## Applications

- Residential LED Lamps: A19 (E26/27, E14), PAR30/38, GU10
- Solid State Lighting





#### PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of the Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

# **Typical Application**

# **Connection Diagram**



# **Ordering Information**

Order Number	Package Type	Package QTY	Supplied As
TPS92314D	SOIC-8	75	Rails
TPS92314DR	SOIC-8	2500	Tape and Reel
TPS92314AD	SOIC-8	75	Rails
TPS92314ADR	SOIC-8	2500	Tape and Reel

# **Pin Descriptions**

Pin	Name	Description	Application Information
1	VCC	Power supply Input	This pin provides power to the internal control , connect a
			10μF~20μF capacitor to ground for filtering.
2	AGND	Small signal Ground	Control signal ground return.
3	ZCD	Zero crossing detection input	The pin senses the voltage of the auxiliary winding for zero current detection.
4	COMP	Compensation network	Output of the error amplifier. Connect a capacitor from this pin to ground to determine the frequency response of average current control loop.
5	DLY	Delay control input	Connect a resistor from this pin to ground to set the delay between switching ON and OFF periods.
6	PGND	Power Ground	Gate driver ground return.
7	ISNS	Current sense voltage feedback	Switching MOSFET current sense pin.
8	GATE	Gate driver output	The output provides the gate driver of the power switching MOSFET.

### Absolute Maximum Ratings (Note 1)

(Note 5)

If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

VCC to GI	ND -0.3V to 40V
DLY,COM	IP,ZCD to GND -0.3V to 7V
ISNS to G	ND -0.3V to 7V
GATE to C	GND (5ns,-6V) -0.3V to 12V
ESD Susc	ceptibility:
HBM ( <i>Not</i>	<i>te 3</i> ) ±2 kV
Storage T	emperature Range -65°C to +150°C
Junction T	emperature (T <sub>J-MAX</sub> ) +150°C
Maximum (Solder an	Lead Temperature nd Reflow) 260°C
Operating Conditions	
Supply Vo	bltage range VCC 13V to 35V
Junction T	emperature (T <sub>J</sub> ) -40°C to +125°C
Thermal F	Resistance (θ <sub>JA</sub> )

**Electrical Characteristics**  $V_{CC} = 18V$  unless otherwise indicated. Typicals and limits appearing in plain type apply for  $T_A = T_J = +25^{\circ}C$ . Limits appearing in **boldface** type apply over the full Operating Temperature Range. Data sheet minimum and maximum specification limits are guaranteed by design, test or statistical analysis.

162°C/W

Symbol	Parameter	Conditions	Min	Typ (Note 4)	Max	Units	
SUPPLY VOLTAGE INPUT (VCC)							
V <sub>CC-UVLO</sub>	VCC Turn on threshold		22.5 / <b>21.7</b>	25.4	28.3 / <b>29.5</b>	V	
	VCC Turn off threshold		10.4 / <b>10.1</b>	12.9	15.3 <b>/ 16.0</b>	V	
	Hysteresis			12.5			
ISTARTUP	Startup Current	V <sub>CC=</sub> V <sub>CC-UVLO</sub> -3.0V		22.2	25.8	μA	
V <sub>CC-OVP</sub>	Over voltage protection threshold		32.7	35.5	38.0	V	
Ivcc	Operating supply	Not switching ,	0.8	1.2	1.8	mA	
	current	65kHz switching		2.3	3.0	mA	
ZERO CRO	SS DETECT (ZCD)						
IZCD	ZCD bais current	$V_{ZCD} = 5V$		0.01	1	uA	
V <sub>ZCD-OVP</sub>	ZCD over-voltage threshold		3.9	4.3	4.7	V	
T <sub>OVP</sub>	Over voltage de- bounce time			3		cycle	
V <sub>ZCD-ARM</sub>	ZCD Arming threshold	V <sub>ZCD</sub> = Increasing	1.04	1.23	1.42	V	
V <sub>ZCD-TRIG</sub>	ZCD Trigger threshold	V <sub>ZCD</sub> = Decreasing	0.48	0.6	0.77	V	
V <sub>ZCD-HYS</sub>	ZCD Hysteresis	V <sub>ZCD-ARM</sub> -V <sub>ZCD-TRIG</sub>		0.61		V	
COMPENS	ATION (COMP)	1	•	•			
I <sub>COMP-</sub> SOURCE	Internal reference current for primary side current regulation	$V_{COMP}$ = 2.0V, $V_{ISNS}$ = 0V, Measure at COMP pin		27		μΑ	
gm <sub>ISNS</sub>	ISNS error amp trans-conductance	$\Delta$ V <sub>ISNS</sub> to $\Delta$ I <sub>COMP</sub> @ V <sub>COMP</sub> = 2.5V		96		µmho	



Symbol	Parameter	Conditions	Min	Typ ( <i>Note 4</i> )	Max	Units
DELAY CO	NTROL (DLY)					
V <sub>DLY</sub>	DLY pin internal		1.21	1.24	1.3	V
	reference voltage					
I <sub>DLY-MAX</sub>	DLY source current	$V_{DLY} = 0V$	250	450		μΑ
CURRENT	SENSE (ISNS)					
V <sub>ISNS-OCP</sub>	Over Current Limit Detection	TPS92314	1.07	1.15	1.22	V
Views age	Over Current Limit	TPS92314A	1 90	20	2 10	
ISNS-OCP	Detection Threshold		1.00	2.0	2.10	
I <sub>ISNS</sub>	Current Sense Bias Current	V <sub>ISNS</sub> = 5V	-1		1	μΑ
T <sub>OCP</sub>	Over current Limit Detection Propagation Delay	Measure ISNS pin pulse width with V <sub>ISNS</sub> = 5V		256		ns
GATE DRIV	/ER (GATE)					
V <sub>GATE-H</sub>	GATE low voltage	IGATE = 50mA source	7.6	9.4		V
V <sub>GATE-L</sub>	GATE high drive voltage	IGATE = 50mA sink		85	125	mV
t <sub>GATE-RISE</sub>	Rise Time	CLOAD = 1nF		94		ns
t <sub>GATE-FALL</sub>	Fall Time	CLOAD = 1nF		16		ns
T <sub>ON-MIN</sub>	Minimum ON time	With ZCD signal.	311	500	900	ns
T <sub>ON-MAX</sub>	Maximum ON time		27	43.9	61	μs
T <sub>OFF-MIN</sub>	Minimum OFF time		1.00	1.50	1.93	μs
T <sub>OFF-MAX</sub>	Maximum OFF time	ZCD = GND	67	117	151	μs
T <sub>OFF-START</sub>	Maximum OFF time when start up.	Maximum OFF time at first 511 switching after UVLO	44	78	102	μs
T <sub>OFF-OCP</sub>	Maximum OFF time when OCP	OFF time when V <sub>ISNS</sub> =4V.		233		μs
THERMAL	SHUTDOWN			•		
TSD	Thermal shutdown temperature	(Note 2)		165		°C
	Thermal Shutdown hysteresis			20		°C

Note 1: Absolute maximum ratings are limits beyond which damage to the device may occur. Operating Ratings are conditions for which the device is intended to be functional, but device parameter specifications may not be guaranteed. For guaranteed specifications and test conditions, see the Electrical Characteristics. All voltages are with respect to the potential at the GND pin, unless otherwise specified.

Note 2: Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at  $T_J = 165^{\circ}C$  (typ.) and disengages at  $T_J = 145^{\circ}C$  (typ).

Note 3: Human Body Model, applicable std. JESD22-A114-C.

Note 4: Typical numbers are at 25°C and represent the most likely norm.

**Note 5:** This  $R_{BJA}$  typical value determined using JEDEC specifications JESD51-1 to JESD51-11. However junction-to-ambient thermal resistance is highly boardlayout dependent. In applications where high maximum power dissipation exists, special care must be paid to thermal dissipation issues during board design. In high-power dissipation applications, the maximum ambient temperature may have to be derated. Maximum ambient temperature ( $T_{A-MAX}$ ) is dependent on the maximum operating junction temperature ( $T_{J-MAX-OP} = 125^{\circ}$ C), the maximum power dissipation of the device in the application ( $P_{D-MAX}$ ), and the junction-to ambient thermal resistance of the part/package in the application ( $R_{BJA}$ ), as given by the following equation:  $T_{A-MAX} = T_{J-MAX-OP} - (R_{BJA} \times P_{D-MAX})$ .



# **Typical Performance Characteristics**

All curves taken at V<sub>CC</sub>=18V with configuration in typical application for driving seven power LEDs with I<sub>LED</sub>=350mA shown in this datasheet.  $T_A=25^{\circ}C$ , unless otherwise specified.







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# Simplified Internal Block Diagram



FIGURE 2. Simplified Block Diagram



#### **Application Information**

The TPS92314/14A is an off-line controller specifically designed to drive LEDs. This device operates in Critical Conduction Mode (CRM) with adaptive Constant ON-Time control, so that high power factor can be achieved naturally. The TPS92314/14A can be configured as an isolated or non-isolated off-line converter. Please refer to TPS92314/14A typical schematic Figure 1, on the front page, in the following discussion. The TPS92314/14A flyback converter consists of a transformer which includes three windings L<sub>P</sub>, L<sub>S</sub> and L<sub>AUX</sub>. An external MOSFET Q<sub>1</sub> and inductor current sensing resistor R<sub>ISNS</sub>. Secondary side components are secondary side transformer winding  $L_s$ , output diode  $D_{OUT}$ , and output capacitor  $C_{OUT}$ . An auxiliary winding is required, and serves two functions. Auxiliary power is developed from the winding to power the TPS92314/14A after start-up, and detect the zero crossing point due to the end of a complete switching cycle. During the on-period, Q<sub>1</sub> is turned on, and current flows through L<sub>P</sub>, Q<sub>1</sub> and R<sub>IGNS</sub> to ground, input energy is stored in the primary inductor L<sub>P</sub>. Simultaneously, the I<sub>SNS</sub> pin of the device monitors the voltage of the current sensing resistor R<sub>ISNS</sub> to perform the cycle-by-cycle inductor current limit function. During the time MOSFET Q1 is off, current flow in L<sub>P</sub> ceases and the energy stored during the on cycle is released to output and auxiliary circuits. During Q<sub>1</sub> off-time current in the secondary winding L<sub>S</sub> charges the output capacitor  $C_{OUT}$  through  $D_{OUT}$  and supplies the LED load. During Q<sub>1</sub> on-time, COLIT is responsible to supply load current to LED load during subsequent on-period. Also during Q1 off-time current is delivered to the auxiliary winding through D<sub>VCC</sub> and powers the TPS92314/14A. The voltage across L<sub>AUX</sub>, V<sub>LAUX</sub> is fed back to the ZCD pin through a resistor divider network formed by RAUX1 and RAUX2 to perform zero crossing detection of VLAUX, which determines the end of the off-period of a switching cycle. The next on period of a new cycle will be initiated after an inserted delay of 2 x t<sub>DLY</sub>. The t<sub>DLY</sub> is programmable by a single resistor connecting the DLY pin and ground. The setting of the delay time, t<sub>DLY</sub> will be described in a separate paragraph. The driver signal ton time width is generated by comparing an internal generated saw-tooth waveform with the voltage on the COMP pin (V<sub>COMP</sub>). Since V<sub>COMP</sub> is slow varying, t<sub>ON</sub> is nearly constant within an AC line cycle. The duration of the off-period (t<sub>OFF</sub>) is determined by the rate of discharging of the secondary current through the transformer. Also,

 $I_{LS-PEAK} = n x I_{LP-PEAK}$ 

where n is the turn ratio of  $L_P$  and  $L_S$ . Figure 3 shows the typical waveforms in normal operation.



FIGURE 3. Primary and Secondary Side Current Waveforms

### **Startup Bias and UVLO**

During startup, the TPS92314/14A is powered from the AC line through R<sub>1</sub> and bridge diode D<sub>1</sub> (Figure 1). In the startup state, most of the internal circuits of the TPS92314/14A are shut down in order to minimize internal quiescent current. When V<sub>CC</sub> reaches the rising threshold of the V<sub>CC-UVLO</sub> (typically 26V), the TPS92314/14A is operating in a low switching frequency mode, where t<sub>ON</sub> and t<sub>OFF</sub> are fixed to 1.5µs and 72µs. When V<sub>ZCD-PEAK</sub> is higher than V<sub>ZCD-ARM</sub>, the TPS92314/14A enters normal operation.





FIGURE 4. Start up Bias Waveforms

#### **Zero Crossing Detection**

To minimized the switching loss of the power MOSFET, a zero crossing detection circuit is embedded in the TPS92314/14A.  $V_{LAUX}$  is AC voltage coupled from  $V_{SW}$  by means of the transformer, with the lower part of the waveform clipped by  $D_{ZCD}$ .  $V_{LAUX}$  is fed back to the ZCD pin to detect a zero crossing point through a resistor divider network which consists of  $R_{AUX1}$  and  $R_{AUX2}$ . The next turn on time of  $Q_1$  is selected  $V_{SW}$  is the minimum, an instant corresponding to a small delay after the zero crossing occurs. (Figure 5) The actual delay time depends on the drain capacitance of the  $Q_1$  and the primary inductance of the transformer ( $L_P$ ). Such delay time is set by a single external resistor as described in Delay Setting section.

During the off-period at steady state,  $V_{ZCD}$  reaches its maximum  $V_{ZCD-PEAK}$  (Figure 3), which is scalable by the turn ratio of the transformer and the resistor divider network  $R_{AUX1}$  and  $R_{AUX2}$ . It is recommended that  $V_{ZCD-PEAK}$  is set to 3V during normal operation.



FIGURE 5. Switching Node Waveforms

### **Delay Time Setting**

In order to reduce EMI and switching loss, the TPS92314/14A inserts a delay between the off-period and the on-period. The delay time is set by a single resistor which connects across the DLY pin and ground, and their relationship is shown in Figure 6. The optimal delay time depends on the resonance frequency between  $L_P$  and the drain to source capacitance of  $Q_1$  ( $C_{DS}$ ). Circuit designers should optimize the delay time according to the following equation.

$$f_{SW} = \frac{1}{2\pi\sqrt{L_P C_{DS}}}$$

$$t_{\text{DLY}} = \frac{\pi \sqrt{L_{\text{P}} C_{\text{DS}}}}{2}$$

After determining the delay time,  $t_{DLY}$  can be implemented by setting  $R_{DLY}$  according to the following equation:

 $R_{DLY} = K_{DLY}(t_{DLY} - 105 ns)$ 

where  $K_{DIY} = 32M\Omega/ns$  is a constant.



FIGURE 6. Delay Time Setting

#### **Protection Features**

#### **OUTPUT OPEN CIRCUIT PROTECTION**

The open circuit protection can be trigger through ZCD pin or VCC pin. If the LED string is disconnected from the output of the TPS92314/14A, The secondly output voltage ( $V_{LED}$ ) and AUX wiring voltage  $V_{ZCD-PEAK}$  will increases. IF  $V_{ZCD-PEAK}$  is greater than  $V_{ZCD-OVP}$  for 3 continues switching cycles or VCC voltage higher than  $V_{CCOVP}$  threshold, Over Voltage Protection (OVP) protection will be trigger. At the meantime, switching of  $Q_1$  will stop and  $V_{CC}$  will decreases until it drops below the falling threshold of  $V_{CC}$ .

#### VCC OVP PROTECTION

The TPS92314/14A has a built-in over voltage protection feature. It can be trigger through the VCC pin when over  $V_{CC-OVP}$  threshold. Once the  $V_{CC-OVP}$  triggered, the output gate signal will pull low and VCC will decrease until it drops below the  $V_{CC-UVLO}$ , the controller will restarts automatically.

#### **OUTPUT SHORT CIRCUIT PROTECTION**

If the LED string is shorted, the voltage of AUX wiring ( $V_{ZCD-PEAK}$ ) will decrease, and as  $V_{ZCD-PEAK}$  voltage decrease below  $V_{ZCD-TRIG}$ , the TPS92314/14A will enter low switching frequency operation. During low switching frequency operation, power supplied from  $L_{AUX}$  to  $V_{CC}$  is not enough to maintain  $V_{CC}$ . If the short remains  $V_{CC}$  will drop below the falling threshold of  $V_{CC-UVLO}$ , the TPS92314/14A will attempt to restart at this time (Figure 7). When the short is removed the TPS92314/14A will restore to steady state operation.





FIGURE 7. Output Short Circuit waveforms

#### **OVER CURRENT PROTECTION**

Over Current Protection (OCP) limits the drain current of MOSFET and prevents inductor / transformer saturation. When  $V_{ISNS}$  reaches a threshold, OCP function will be triggered, controller gate drive will pull low and OFF time will extends to 233µs, also  $C_{COMP}$  capacitor will be discharged by internal switch and gate drive ON time will force to minimum in next cycle.

#### THERMAL PROTECTION

Thermal protection is implemented by an internal thermal shutdown circuit, which activates at 165°C (typically). In this case, the switching power MOSFET will turn off. Capacitor  $C_{VCC}$  will discharge until UVLO. If the junction temperature of the TPS92314/14A falls back below 145°C, the TPS92314/14A resumes normal operation.



FIGURE 8. Auto Restart Operation



### **Design Example**

The following design example illustrates the procedures to calculate the external component values for the TPS92314/14A isolated single stage fly-back LED driver with PFC.

#### Design Specifications:

Input voltage range,  $V_{AC\_RMS} = 85VAC - 132VAC$ Nominal input voltage,  $V_{AC\_RMS(NOM)} = 110VAC$ Number of LED in serial =7 LED current,  $I_{LED} = 350mA$ Forward voltage drop of single LED = 3.0V Forward voltage of LED stack,  $V_{LED} = 21V$ 

#### Key operating Parameters:

Converter minimum switching frequency,  $f_{SW} = 75$ kHz Output rectifier maximum reverse voltage,  $V_{DOUT(MAX)} = 100V$ Power MOSFET rating,  $V_{Q1(MAX)} = 800V$ Power MOSFET Output Capacitance,  $C_{DS} = 37$ pF (estimated) Nominal output power,  $P_{OUT} = 8W$ 

## **START UP BIAS RESISTOR**

During start up, the V<sub>CC</sub> will be powered by the rectified line voltage through external resistor, R<sub>1</sub>. The V<sub>CC</sub> start up current, I<sub>VCC</sub> (SU) must set in the range I<sub>VCC(MIN)</sub> > I<sub>VCC(SU)</sub> > I<sub>STARTUP(MAX)</sub> to ensure proper restart operation during OVP fault at maximum voltage input. In this example, a value of 0.88mA is suggested. The resistance of R<sub>1</sub> can be calculated by dividing the nominal input voltage in RMS by the start up current suggested.

So,  $R_{AC} = 132V / 0.88mA = 150K\Omega$  is recommended.

## **TRANSFORMER TURN RATIO**

The transformer winding turn ratio, n is governed by the MOSFET Q1 maximum rated voltage,  $(V_{Q1(MAX)})$ , highest line input peak voltage  $(V_{AC-PEAK})$  and output diode maximum reverse voltage rating  $(V_{OUT(MAX)})$ . The output diode rating limits the lower bound of the turn ratio and the power MOSFET rating provide the upper bound of the turn ratio. The transformer turn ratio must be selected in between the bounds. If the maximum reverse voltage of  $D_{OUT}$   $(V_{DOUT(MAX)})$  is 100V. the minimum transformer turn ratio can be calculated with the equation in below.

$$n > \frac{V_{AC-PEAK}}{(V_{DOUT}(MAX) - V_{LED})}$$
$$n > \frac{132x\sqrt{2}}{100 - 30} = 2.33$$

In operation, the voltage at the switching node,  $V_{SW}$  must be small than the MOSFET maximum rated voltage  $V_{Q1(MAX)}$ , For reason of safety, 10% safety margin is recommended. Hence, 90% of  $V_{Q1(MAX)}$  is used in the following equation.

$$n < \frac{V_{Q1(MAX)} \times 0.9 - V_{AC-PEAK} - V_{os}}{V_{LED(MAX)}}$$

$$n < \frac{800 \times 0.9 - 132 \sqrt{2 - 50}}{30} = 18.8$$

where  $V_{OS}$  is the maximum switching node overshoot voltage allowed, in this example, 50V is assumed. As a rule of thumb, lower turn ratio of transformer can provide a better line regulation and lower secondly side peak current. In here, turn ratio n = 3.8 is recommended.

# SWITCHING FREQUENCY SELECTION

TPS92314/14A can operate at high switching frequency in the range of 60kHz to 150kHz. In most off-line applications, with considering of efficiency degradation and EMC requirements, the recommended switching frequency range will be 60kHz to 80kHz. In this design example, switching frequency at 75kHz is selected.

# SWITCHING ON TIME

The maximum power switch on-time,  $t_{ON}$  depends on the low line condition of  $85V_{AC}$ . At  $85V_{AC}$  the switching frequency was chosen at 75kHz. This transformer design will follow the formulae as shown below.





### TRANSFORMER PRIMARY INDUCTANCE

The primary inductance,  $L_P$  of the transformer is related to the minimum operating switching frequency  $f_{SW}$ , converter output power  $P_{OUT}$ , system efficiency  $\eta$  and minimum input line voltage  $V_{AC\_RMS(MIN)}$ . For CRM operation, the output power,  $P_{OUT}$  can be described by the equation in below.

$$P_{OUT} = \eta x \frac{1}{2} L_P x I_{LP-PEAK}^2 x f_{SW}$$

By re-arranging terms, the transformer primary inductance required in this design example can be calculated with the equation follows:

$$L_{P} = \frac{\eta x V_{AC\_RMS(MIN)}^{2} t_{ON}^{2}}{2 x P_{OUT} x \frac{1}{f_{EW}}}$$

The converter minimum switching frequency is 75kHz,  $t_{ON}$  is 5.3µs,  $V_{AC\_RMS(MIN)}$  = 85V and  $P_{OUT}$  = 8W, assume the system efficiency,  $\eta$  = 85%. Then,

$$L_{\rm P} = \frac{0.85 \, x (85)^2 \, x (5.3 \, \mu)^2}{2 x 8 x 13.3 \, \mu} = 0.81 \, \text{mH}$$

From the calculation in above, the inductance of the primary winding required is 0.81mH.

#### Calculate The Current Sensing Resistor

After the primary inductance and transformer turn ratio is determined, the current sensing resistor,  $R_{ISNS}$  can be calculated. The resistance for  $R_{ISNS}$  is governed by the output current and transformer turn ratio, the equation in below can be used.

$$\mathsf{R}_{\mathsf{ISNS}} = \mathsf{n} \mathsf{x} \left( \frac{\mathsf{v}_{\mathsf{REF}}}{\mathsf{I}_{\mathsf{LED}}} \right)$$

where  $V_{\text{REF}}$  is fixed to 0.14V internally.

Transformer turn ratio,  $N_P$ :  $N_S$  is 3.8 : 1 and  $I_{LED} = 0.35A$ 

$$R_{\rm ISNS} = 3.8 \times \frac{0.14}{0.35} = 1.52 \Omega$$

In Figure 9, resistor R<sub>FILTER</sub> is used to reduce the high frequency noise into ISNS pin. the typical value is 300 x R<sub>ISNS</sub>.



FIGURE 9. R<sub>ISNS</sub> Resistor Interface





FIGURE 10. Auxiliary Winding Interface to ZCD

# **Auxiliary Winding Interface To ZCD**

In Figure 10,  $R_{AUX1}$  and  $R_{AUX2}$  forms a resistor divider which sets the thresholds for over voltage protection of  $V_{LED}$ ,  $V_{ZCD-OVP}$ , and  $V_{ZCD-PEAK}$ . Before the calculation, we need to set the voltage of the auxiliary winding,  $V_{LAUX}$  at open circuit. For example :

Assume the nominal forward voltage of LED stack (V<sub>LED</sub>) is 21V.

To avoid false triggering  $ZCD_{OVP}$  voltage threshold at normal operation, select  $ZCD_{OVP}$  voltage at 1.3 times of the V<sub>LED</sub> is typical in most applications. In case the transformer leakage is higher, the  $ZCD_{OVP}$  threshold can be set to 1.5 times of the V<sub>LED</sub>.

In this design example, open circuit AUX winding OVP voltage threshold is set to 30V. Assume the current through the AUX winding is 0.4mA typical.

As a result,  $R_{AUX1}$  is 66k $\Omega$  and  $R_{AUX2}$  is 12k $\Omega$ .

# Auxiliary Winding V<sub>cc</sub> Diode Selection

The VCC diode D<sub>VCC</sub> provides the supply current to the converter, low temperature coefficient , low reverse leakage and ultra fast diode is recommended.

### **Compensation Capacitor And Delay Timer Resistor Selection**

To achieve PFC function with a constant on time flyback converter, a low frequency response loop is required. In most applications, a  $4.7\mu$ F C<sub>COMP</sub> capacitor is suitable for compensation.



FIGURE 11. Compensation and DLY Timer connection

The resistor  $R_{DLY}$  connecting the DLY pin to ground is used to set the delay time between the ZCD trigger to power MOSFET turn on. The delay time required can be calculated with the parasitic capacitance at the drain of MOSFET to ground and primary inductance of the transformer. Equation in below can be used to find the delay time and Figure 6 in previous page can help to find the resistance once the delay time is calculated

$$t_{DLY} = \frac{\pi \sqrt{L_P C_{DS}}}{2}$$

For example, using a transformer with primary inductance  $L_P = 1$ mH, and power MOSFET drain to ground capacitor  $C_{DS}=37$ pF, the  $t_{DLY}$  can be calculated by the upper equation. As a result,  $t_{DLY}=302$ ns and  $R_{DLY}$  is 6.31k $\Omega$ . The delay time may need to change according to the primary inductance of the transformer. The typical level of output current will shift if inappropriate delay time is chosen.

### **Output Flywheel Diode Selection**

To increase the overall efficiency of the system, a low forward voltage schottky diode with appropriate rating should be used.



## **Primary Side Snubber Design**

The leakage inductance can induce a high voltage spike when power MOSFET is turned off. Figure 12 illustrate the operation waveform. A voltage clamp circuit is required to protect the power MOSFET. The voltage of snubber clamp ( $V_{SN}$ ) must be higher than the sum of over shoot voltage ( $V_{OS}$ ), LED open load voltage multiplied by the transformer turn ratio (n). In this examples, the  $V_{OS}$  is 50V and LED maximum voltage,  $V_{LED(MAX)}$  is 30V, transformer turn ratio is 3.8. The snubber voltage required can be calculated with following equations.



#### FIGURE 12. Snubber Waveform

$$V_{SN} > V_{OS} + V_{LED(MAX)} \times n$$

where n is the turn ratio of the transformer.

At the same time, sum of the snubber clamp voltage and  $V_{AC}$  peak voltage ( $V_{AC\_PEAK}$ ) must be smaller than the MOSFET breakdown voltage ( $V_{MOS\_BV}$ ). By re-arranging terms, equation in below can be used.

In here, snubber clamp voltage,  $V_{SN} = 250V$  is recommended.

### **Output Capacitor**

The capacitance of the output capacitor is determined by the equivalent series resistance (ESR) of the LED, R<sub>LED</sub> and the ripple current allowed for the application. The equation in below can be used to calculate the required capacitance.

$$C_{OUT} = \frac{\sqrt{\left(2\frac{J_{LED}}{\Delta I_{LED}}\right)^2 - 1}}{4 \times \pi \times f_{AC} R_{LED}}$$

Assume the ESR of the LED stack contains 7 LEDs and is 2.6 $\Omega$ , AC line frequency f<sub>AC</sub> is 60Hz. In this example, LED current I<sub>LED</sub> is 350mA and output ripple current is 30% of I<sub>LED</sub>:

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$$C_{OUT} = \frac{\sqrt{\left(\frac{2x0.35}{0.3x0.35}\right)^2 - 1}}{4x\pi x 60x7x2.6}$$

Then,  $C_{OUT} = 480 \mu F$ .

In here, a 470µF output capacitor with 10µF ceramic capacitor in parallel is suggested.

### **PCB Layout Considerations**

The performance of any switching power supplies depend as much upon the layout of the PCB as the component selection. Good layout practices are important when constructing the PCB. The layout must be as neat and compact as possible, and all external components must be as close as possible to their associated pins. High current return paths and signal return paths must be separated and connect together at single ground point. All high current connections must be as short and direct as possible with thick traces. The drain voltage of the MOSFET should be connected close to the transformer pin with short and thick trace to reduce



potential electromagnetic interference. For off-line applications, one more consideration is the safety requirements. The clearance and creepage to high voltage traces must be complied to all applicable safety regulations.



FIGURE 13. Isolated topology schematic



FIGURE 14. Non-isolated topology schematic



# Physical Dimensions inches (millimeters) unless otherwise noted



# Notes