# INTEGRATED CIRCUITS

# DATA SHEET

# 74ALVCHS162830

18-bit to 36-bit address driver with bus hold (3-State)

Product data 2001 Sep 07

File under Integrated Circuits — ICL03





# 18-bit to 36-bit address driver with bus hold (3-State) 74ALVCHS162830

#### **FEATURES**

- ullet Output ports have equivalent 26  $\Omega$  series resistors, so no external resistors are required
- Diodes on inputs clamp overshoot
- ESD classification testing is done to JEDEC Standard JESD22.
   Protection exceeds 2000 V HBM per method A114.
- Latch-up testing is done to JEDEC Standard JESD78, which exceeds 100 mA.
- Bus hold on data inputs eliminates the need for external pullup/pulldown resistors
- Packaged in thin very small-outline package (TVSOP) 0.4 mm pitch
- Optimized for use with PCK953 in SDRAM module applications
- Balanced ±12 mA output drive
- Low noise, low skew

#### **DESCRIPTION**

The ALVCHS162830 address driver is designed for 2.3 V to 3.6 V  $\mbox{V}_{CC}$  operation.

Diodes to V<sub>CC</sub> have been added on the inputs to clamp overshoot.

The bus hold feature retains the inputs' last state whenever the input bus goes to high impedance. This prevents floating inputs and eliminates the need for pull up or pull down resistors.

The outputs, which are designed to sink up to 12 mA, include equivalent 26  $\Omega$  series resistors to reduce overshoot and undershoot.

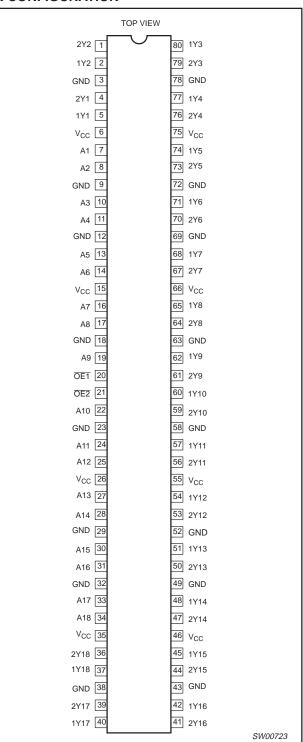
To ensure the high-impedance state during power up or power down, the output-enable  $(\overline{\text{OE}})$  input should be tied to  $V_{CC}$  through a pullup resistor; the minimum value of the resistor is determined by the current-sinking capability of the driver.

The 74ALVCHS162830 is characterized for operation from -40 to  $+85~^{\circ}\text{C}$ .

### **FUNCTION TABLE**

	Inputs		Outputs			
OE1	OE2	Α	1Yn	2Yn		
L	Н	Н	Н	Z		
L	Н	L	L	Z		
Н	L	H Z		Н		
Н	L	L	Z	L		
L	L	Н	Н	Н		
L	L	L	L	L		
Н	Н	Х	Z	Z		

#### **PIN CONFIGURATION**



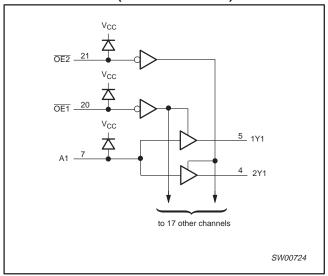
# ORDERING INFORMATION

PACKAGES	TEMPERATURE RANGE	ORDER CODE	DWG NUMBER	
80-pin plastic thin very small outline (TVSOP)	−40 to +85 °C	74ALVCHS162830DGB	SOT647-1	

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### **LOGIC DIAGRAM (POSITIVE LOGIC)**



### **PIN DESCRIPTION**

PIN(S)	SYMBOL	FUNCTION
6, 15, 26, 35, 46, 55, 66, 75	V <sub>CC</sub>	Supply voltage
7, 8, 10, 11, 13, 14, 16, 17, 19, 22, 24, 25, 27, 28, 30, 31, 33, 34	An	Inputs
1, 2, 4, 5, 36, 37, 39, 40, 41, 42, 44, 45, 47, 48, 50, 51, 53, 54, 56, 57, 59, 60, 61, 62, 64, 65, 67, 68, 70, 71, 73, 74, 76, 77, 79, 80	1Yn, 2Yn	Outputs
20, 21	OE1, OE2	Output enable
3, 9, 12, 18, 23, 29, 32, 38, 43, 49, 52, 58, 63, 69, 72, 78	GND	Ground

# **ABSOLUTE MAXIMUM RATINGS**

Over recommended operating free-air temperature range (unless otherwise noted).<sup>1</sup>

SYMBOL	PARAMETER	CONDITIONS	RATING	UNIT
V <sub>CC</sub>	Supply voltage range		-0.5 to +4.6	V
VI	Input voltage range	See Note 2	-0.5 to +4.6	V
Vo	Output voltage range	See Notes 2 and 3	–0.5 to V <sub>CC</sub> +0.5	V
I <sub>IK</sub>	Input clamp current	V <sub>1</sub> < 0	<b>–</b> 50	mA
I <sub>OK</sub>	Output clamp current	V <sub>O</sub> < 0	<b>–</b> 50	mA
I <sub>O</sub>	Continuous output current		±50	mA
I <sub>CC</sub> , I <sub>GND</sub>	Continuous current through each V <sub>CC</sub> or GND		±100	mA
$\Theta_{JA}$	Package thermal impedance	See Note 4	106	°C/W
T <sub>stg</sub>	Storage temperature range		-65 to +150	°C

#### NOTES:

- Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings
  only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating
  conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- 2. The input negative-voltage and output voltage ratings may be exceeded if the input and output current ratings are observed.
- 3. This value is limited to 4.6 V maximum.
- 4. The package thermal impedance is calculated in accordance with JESD 51.

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# **RECOMMENDED OPERATING CONDITIONS**

All unused control inputs of the device must be held at  $V_{CC}$  or GND to ensure proper device operation.

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SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNIT		
V <sub>CC</sub>	Supply voltage		2.3	3.6	V		
V	I limb level in motor the me	V <sub>CC</sub> = 2.3 V to 2.7 V	1.7		V		
$V_{IH}$	High-level input voltage	V <sub>CC</sub> = 2.7 V to 3.6 V	2		<b>1</b>		
V	Law law line of walks and	V <sub>CC</sub> = 2.3 V to 2.7 V		0.7	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \		
$V_{IL}$	Low-level input voltage	V <sub>CC</sub> = 2.7 V to 3.6 V		0.8	<b>-</b>		
VI	Input voltage		0	V <sub>CC</sub>	V		
Vo	Output voltage		0	V <sub>CC</sub>	V		
		V <sub>CC</sub> = 2.3 V		-6			
I <sub>OH</sub>	High-level output current	V <sub>CC</sub> = 2.7 V		-8	mA		
		V <sub>CC</sub> = 3 V		-12	1		
		V <sub>CC</sub> = 2.3 V		6			
I <sub>OL</sub>	Low-level output current	V <sub>CC</sub> = 2.7 V		8	mA		
		V <sub>CC</sub> = 3 V		12	1		
Δt/Δν	Input transition rise or fall rate			10	ns/V		
T <sub>amb</sub>	Operating free-air temperature		-40	+85	°C		

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### **ELECTRICAL CHARACTERISTICS**

Over recommended operating free-air temperature range (unless otherwise noted).

SYMBOL	PARAMETER	TEST CON	IDITIONS	V <sub>CC</sub>	MIN	TYP <sup>1</sup>	MAX	UNIT
		I <sub>I</sub> = -18 mA	2.3 V			-1.2	V	
$V_{IK}$		I <sub>I</sub> = 18 mA	2.3 V			V <sub>CC</sub> +1.2	1 '	
		I <sub>OH</sub> = -100 μA		2.3 V to 3.6 V	V <sub>CC</sub> -0.2			
		$I_{OH} = -4 \text{ mA}, V_{IH} = 1.7 \text{ V}$	/	2.3 V	1.9			]
$V_{OH}$		I <sub>OH</sub> = -6 mA	V <sub>IH</sub> = 1.7 V	2.3 V	1.7			V
		IOH = -0 IIIA	V <sub>IH</sub> = 2 V	3 V	2.4			]
		$I_{OH} = -8 \text{ mA}, V_{IH} = 2 \text{ V}$		2.7 V	2			]
		$I_{OH} = -12 \text{ mA}, V_{IH} = 2 \text{ V}$	3 V	2			1	
		I <sub>OL</sub> = 100 μA		2.3 V to 3.6 V			0.2	
		$I_{OL} = 4 \text{ mA}, V_{IL} = 0.7 \text{ V}$	$I_{OL} = 4 \text{ mA}, V_{IL} = 0.7 \text{ V}$				0.4	1
V <sub>OL</sub>			V <sub>IL</sub> = 0.7 V	2.3 V			0.55	V
	$I_{OL} = 6 \text{ mA}$	V <sub>IL</sub> = 0.8 V	3 V			0.55	1	
		$I_{OL} = 8 \text{ mA}, V_{IL} = 0.8 \text{ V}$		2.7 V			0.6	1
		$I_{OL} = 12 \text{ mA}, V_{IL} = 0.8 \text{ V}$	3 V			0.8		
I <sub>I</sub>		$V_I = V_{CC}$ or GND		3.6 V			±5	μА
		V <sub>I</sub> = 0.7 V		2.3 V	45			
		V <sub>I</sub> = 1.7 V		2.3 V	-45			1
I <sub>I(hold)</sub>		V <sub>I</sub> = 0.8 V		3 V	75			μΑ
		V <sub>I</sub> = 2 V		3 V	-75			1
		$V_1 = 0 \text{ to } 3.6 \text{ V}^2$	$V_1 = 0 \text{ to } 3.6 \text{ V}^2$				±500	1
I <sub>OZ</sub>		$V_O = V_{CC}$ or GND		3.6 V			±10	μА
I <sub>CC</sub>		$V_I = V_{CC}$ or GND, $I_O = 0$		3.6 V			40	μΑ
Δl <sub>CC</sub>		One input at $V_{CC}$ – 0.6 V, Other inputs at $V_{CC}$ or GND		3 V to 3.6 V			750	μΑ
	Control inputs	V <sub>I</sub> = V <sub>CC</sub> or GND		221/		3.5		, r
C <sub>i</sub>	Data inputs			3.3 V		7.64		pF
Co	Outputs	$V_O = V_{CC}$ or GND		3.3 V		3.12		pF

All typical values are at V<sub>CC</sub> = 3.3 V, T<sub>amb</sub> = 25°C.
 This is the bus-hold maximum dynamic current. It is the minimum overdrive current required to switch the input from one state to another.

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### **SWITCHING CHARACTERISTICS**

Over recommended operating free-air temperature range (unless otherwise noted) (see Figures 1 and 2).

PARAMETER FROM		ROM TO		$V_{CC}$ = 2.5 V $\pm$ 0.2 V		V <sub>CC</sub> = 2.7 V		$V_{CC}$ = 3.3 V $\pm$ 0.3 V	
TAKAWILTEK	(INPUT)	(OUTPUT)	MIN	MAX	MIN	MAX	MIN	MAX	UNIT
t <sub>pd</sub>	А	Υ	1.2	3.8		4	1.7	3.5	ns
t <sub>en</sub>	ŌĒ	Υ	1	5.7		5.7	1	4.8	ns
t <sub>dis</sub>	ŌĒ	Υ	1	4.9		5.4	1.7	5.2	ns
t <sub>sk(o)</sub> 1	Output skew	_	-	-	_	_	-	500	ps

# OPERATING CHARACTERISTICS, T<sub>amb</sub> = 25°C

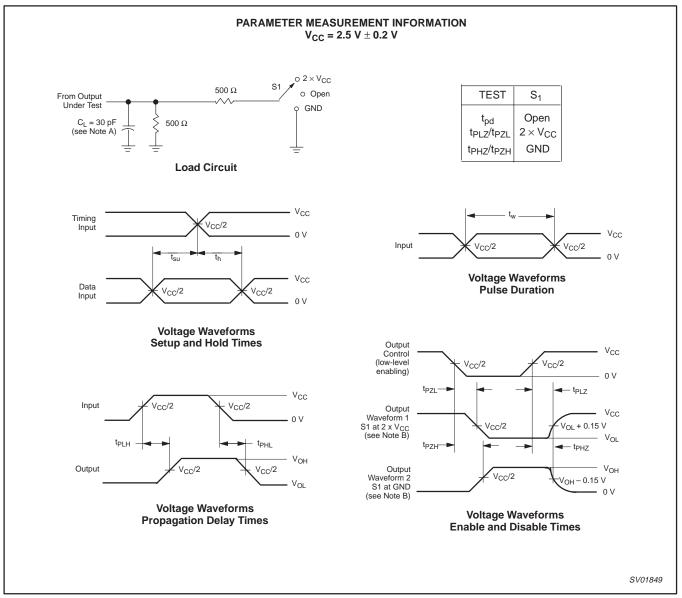
SYMBOL	DADA	METER	TEST CONDITIONS	$V_{CC}$ = 2.5 V $\pm$ 0.2 V	$V_{CC}$ = 3.3 V $\pm$ 0.3 V	UNIT	
STWIBOL PARAMETER		WEIEK	TEOT CONDITIONS	TYP	TYP	Jiiii	
	Power dissipation	All outputs enabled	C <sub>1</sub> = 0. f = 10 MHz	49	53	pF	
C <sub>pd</sub>	capacitance per driver	All outputs disabled	O <sub>L</sub> = 0, 1 = 10 MH2	6	7.5	þΓ	

NOTE:

1. Output skew between any 2 outputs of same part switching in the same direction.

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#### NOTES:

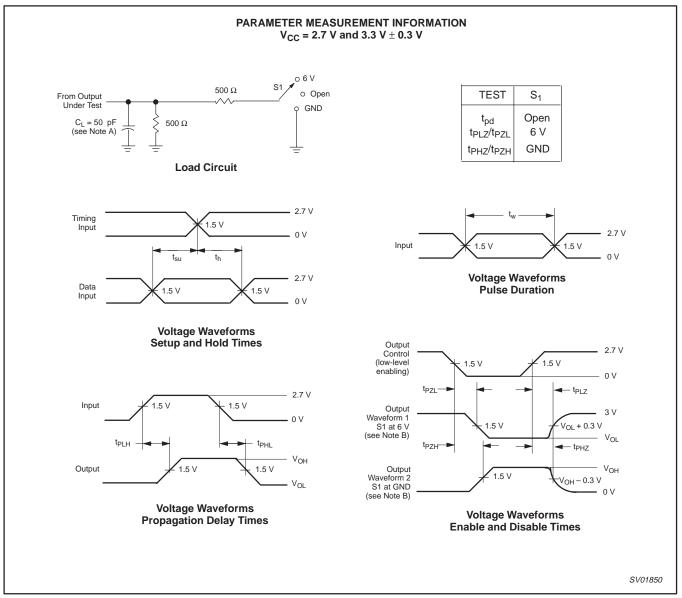
- A. C<sub>L</sub> includes probe and jig capacitance.
- B. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
- C. All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  10 MHz,  $Z_O = 50~\Omega$ ,  $t_f \leq$  2 ns,  $t_f \leq$  2 ns.
- D. The outputs are measured one at a time with one transition per measurement.
- E.  $t_{PLZ}$  and  $t_{PHZ}$  are the same as  $t_{dis}$ .
- F.  $t_{PZL}$  and  $t_{PZH}$  are the same as  $t_{en}$ .
- G. t<sub>PLH</sub> and t<sub>PHL</sub> are the same as t<sub>pd</sub>.

Figure 1. Load circuit and voltage waveforms

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#### NOTES:

- A. C<sub>L</sub> includes probe and jig capacitance.
- B. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
- C. All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  10 MHz,  $Z_O = 50~\Omega$ ,  $t_f \leq 2.5~ns$ ,  $t_f \leq 2.5~ns$ .
- D. The outputs are measured one at a time with one transition per measurement.
- E.  $t_{PLZ}$  and  $t_{PHZ}$  are the same as  $t_{dis}$ .
- F.  $t_{PZL}$  and  $t_{PZH}$  are the same as  $t_{en}$ .
- G.  $t_{PLH}$  and  $t_{PHL}$  are the same as  $t_{pd}$ .

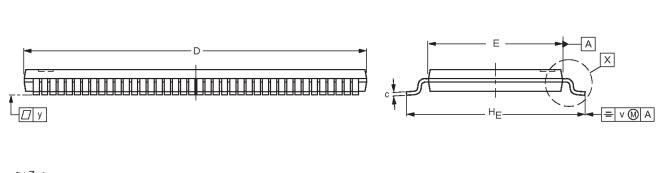
Figure 2. Load circuit and voltage waveforms

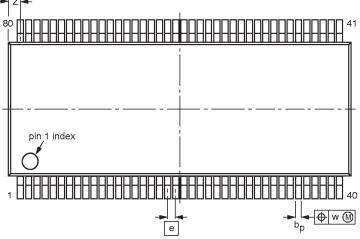
# 18-bit to 36-bit address driver with bus hold (3-State)

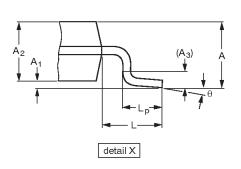
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# TSSOP80: plastic thin shrink small outline package; 80 leads; body width 6.1 mm

SOT647-1







0 2.5 5 mm scale

### DIMENSIONS (mm are the original dimensions).

UN	IIT	A max.	Α1	A <sub>2</sub>	А3	bp	С	D <sup>(1)</sup>	E <sup>(2)</sup>	е	HE	L	Lp	٧	w	у	z	θ
m	m	1.2	0.15 0.05	1.05 0.85	0.25	0.23 0.13	0.2 0.1	17.1 16.9	6.2 6.0	0.4	8.3 7.9	1.0	0.75 0.45	0.2	0.07	0.08	0.84 0.57	8° 0°

#### Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFERENCES					ISSUE DATE
VERSION	IEC	JEDEC EIAJ			PROJECTION	ISSUE DATE	
SOT647-1		MO-153					00-08-21

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### Data sheet status

Data sheet status <sup>[1]</sup>	Product status <sup>[2]</sup>	Definitions
Objective data	Development	This data sheet contains data from the objective specification for product development.  Philips Semiconductors reserves the right to change the specification in any manner without notice.
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<sup>[1]</sup> Please consult the most recently issued data sheet before initiating or completing a design.

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Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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